

FEATURES

- A Guaranteed Start-Up from less than 0.9 V.
- High Efficiency.
- Low Quiescent Current.
- Less Number of External Components needed.
- Low Ripple and Low Noise.
- Fixed Output Voltage: 2.7, 3.0V, 3.1V, 3.3V, 3.6V , 5V and 5.5V .
- Driver for External Transistor.
- Space Saving package: SOT-23, SOT-89 and TO-92.

APPLICATIONS

- Pagers.
- Cameras.
- Wireless Microphones.
- Pocket Organizers.
- Battery Backup Suppliers.
- Portable Instruments.

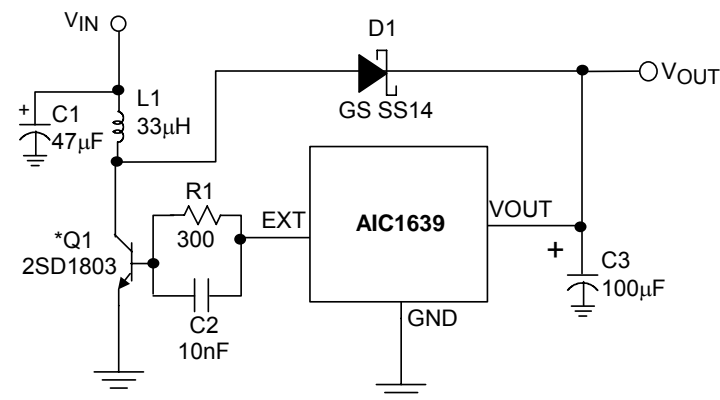
DESCRIPTION

The AIC1639 is a high efficiency step-up DC/DC controller for applications using 1 to 4 battery cells. Only three external components are required to deliver a fixed output voltage of 2.7, 3.0V, 3.1V, 3.3V, 3.6V , 5V or 5.5V. The AIC1639 starts up from less than 0.9V input with 1mA load. Pulse Frequency Modulation scheme brings optimized performance for applications with light output loading and low input voltages. The output ripple and noise are lower compared with the circuits operating in PSM mode.

The PFM control circuit operating in 100KHz (max.) switching rate results in smaller passive components. The space saving SOT-23, SOT-89 and TO-92 packages make the AIC1639 an ideal choice of DC/DC controller for space conscious applications, like pagers, electronic cameras, and wireless microphones.

Provided with an external transistor driver pin (EXT), the AIC1639 is recommended for applications requiring current as large as several tens to several hundreds of milli-amperes.

TYPICAL APPLICATION CIRCUIT



*Q1: Sanyo 25D1803S-TC 60V/5A/20W

100mA Load Current Step-Up Converter

ORDERING INFORMATION

AIC1639-XX X X XX

PACKING TYPE
TR: TAPE & REEL
BG: BAG

PACKAGE TYPE
X: SOT-89
Z: TO-92
U: SOT-23

C: Commercial
P: Lead Free Commercial
G: Green Package

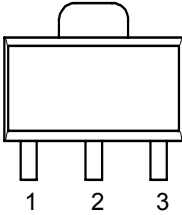
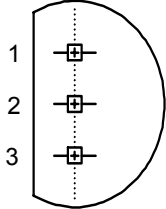
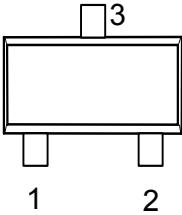
OUTPUT VOLTAGE
27: 2.7V
30: 3.0V
31: 3.1V
33: 3.3V
36: 3.6V
50: 5.0V

EX: AIC1639-27CXTR

→ 2.7V Version, in SOT-89 Package & TR
Packing Type

AIC1639-27PXTR

→ 2.7V Version, in SOT-89 Lead Free
Package & TR Packing Type

ORDERING INFORMATION	
<p>SOT-89 TOP VIEW 1: GND 2: VOUT 3: EXT</p>	
<p>TO-92 TOP VIEW 1: GND 2: VOUT 3: EXT</p>	
<p>SOT-23 TOP VIEW 1: GND 2: EXT 3: VOUT</p>	

● SOT-23 MARKING

Part No.	CU	PU	GU
AIC1639-27	DB27	DB27P	DB27G
AIC1639-30	DB30	DB30P	DB30G
AIC1639-31	DB31	DB31P	DB31G
AIC1639-33	DB33	DB33P	DB33G
AIC1639-36	DB36	DB36P	DB36G
AIC1639-50	DB50	DB50P	DB50G
AIC1639-55	DB55	DB55P	DB55G

● SOT-89 MARKING

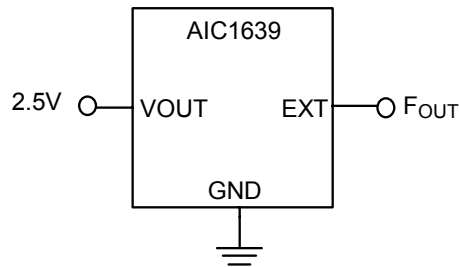
Part No.	CX	PX	GX
AIC1639-27XX	AU27	AU27P	AU27G
AIC1639-30XX	AU30	AU30P	AU30G
AIC1639-31XX	AU31	AU31P	AU31G
AIC1639-33XX	AU33	AU33P	AU33G
AIC1639-36XX	AU36	AU36P	AU36G
AIC1639-50XX	AU50	AU50P	AU50G
AIC1639-55XX	AU55	AU55P	AU55G

■ ABSOLUTE MAXIMUM RATINGS

Supply Voltage (VOUT Pin)	6V
EXT pin Voltage	-0.3V to Vout+0.3V
EXT pin Current	± 50mA
Operating Temperature Range	-40°C to 85°C
Maximum Junction Temperature	125°C
Storage Temperature Range	-65°C to 150 °C
Lead Temperature (Soldering 10 Sec.)	260°C
Thermal Resistance Junction to Case	SOT-23.....	130°C/W
	TO-92.....	120°C/W
	SOT-89.....	30°C/W
Thermal Resistance Junction to Ambient	SOT-23.....	180°C/W
(Assume no ambient airflow, no heatsink)	TO-92.....	150°C/W
	SOT-89.....	160°C/W

Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

■ TEST CIRCUIT



Oscillator Test Circuit

■ ELECTRICAL CHARACTERISTICS ($T_A=25^\circ\text{C}$, $I_O=10\text{mA}$, Unless otherwise specified) (Note1)

PARAMETER	TEST CONDITIONS	SYMBOL	MIN.	TYP.	MAX.	UNIT
Output Voltage	AIC1639-27 $V_{IN}=1.8\text{V}$	V_{OUT}	2.633	2.700	2.767	V
	AIC1639-30 $V_{IN}=1.8\text{V}$		2.925	3.000	3.075	
	AIC1639-31 $V_{IN}=1.8\text{V}$		3.022	3.100	3.177	
	AIC1639-33 $V_{IN}=2.0\text{V}$		3.218	3.300	3.382	
	AIC1639-36 $V_{IN}=2.0\text{V}$		3.510	3.600	3.690	
	AIC1639-50 $V_{IN}=3.0\text{V}$		4.875	5.000	5.125	
	AIC1639-55 $V_{IN}=3.0\text{V}$		5.265	5.500	5.637	
Input Voltage		V_{IN}			6	V
Start-Up Voltage	$I_{OUT}=1\text{mA}$, $V_{IN}:0 \rightarrow 2\text{V}$	V_{START}		0.8	0.9	V
Hold-on Voltage	$I_{OUT}=1\text{mA}$, $V_{IN}:2 \rightarrow 0\text{V}$	V_{HOLD}	0.6			V
No-Load Input Current	$I_{OUT}=0\text{mA}$	I_{IN}		18		μA
Supply Current 1	AIC1639-27	I_{DD1}		45		μA
	AIC1639-30			50		
	AIC1639-31			55		
	AIC1639-33			60		
	AIC1639-36			65		
	AIC1639-50			80		
	AIC1639-55			85		
	EXT at no load, $V_{IN}=V_{OUT} \times 0.95$ Measurement of the IC input current (VOUT Pin)					
Supply Current 2	EXT at no load, $V_{IN}=V_{OUT} + 0.95$ Measurement of the IC input current (VOUT Pin)	I_{DD2}		7		μA
EXT "H" On-Resistance	AIC1639-27	R_{EXTH}		300		Ω
	AIC1639-30			200		
	AIC1639-31			195		
	AIC1639-33			185		
	AIC1639-36			170		
	AIC1639-50			130		
	AIC1639-55			120		
$V_{EXT}=V_{OUT} - 0.4\text{V}$						
EXT "L" On-Resistance	AIC1639-27	R_{EXTL}		110		Ω
	AIC1639-30			80		

	AIC1639-31		75	
	AIC1639-33		70	
	AIC1639-36		65	
	AIC1639-50		60	
	AIC1639-55		55	
	$V_{EXT} = 0.4V$			

■ ELECTRICAL CHARACTERISTICS (Continued)

PARAMETER	TEST CONDITIONS	SYMBOL	MIN.	TYP.	MAX.	UNIT
Oscillator Duty Cycle	$V_{IN} = V_{OUT} \times 0.95$ Measurement of the EXT Pin Waveform	DUTY	65	75	85	%
Max. Oscillator Freq.	$V_{IN} = V_{OUT} \times 0.95$ Measurement of the EXT Pin Waveform	F_{OSC}	80	105	130	KHz
Efficiency		η		80		%

Note 1: Specifications are production tested at $T_A = 25^\circ C$. Specifications over the $-40^\circ C$ to $85^\circ C$ operating temperature range are assured by design, characterization and correlation with Statistical Quality Controls (SQC).

TYPICAL PERFORMANCE CHARACTERISTICS

Inductor (L1) : 33 μ H (Pin Type)

Capacitor (C1) : 47 μ F (Tantalum Type)

Diode (D1) : 1N5819 Schottky Type

Transistor (Q1) : 2SD1803

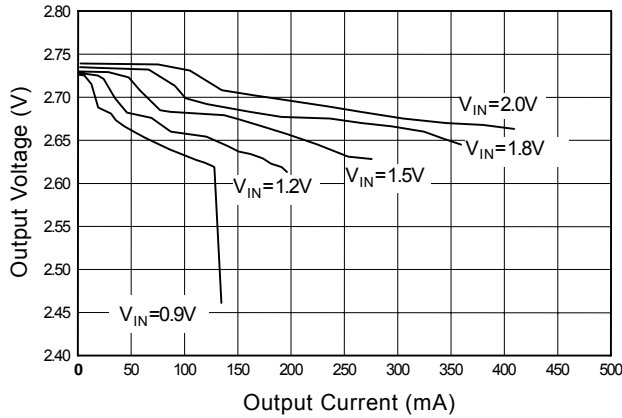


Fig. 1 AIC1639-27 Load Regulation (L=33 μ H)

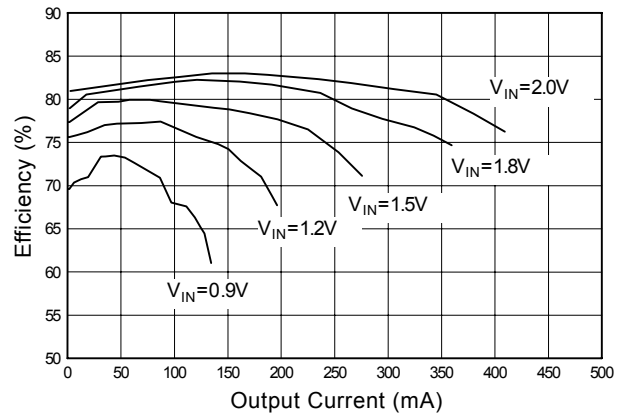


Fig. 2 AIC1639-27 Efficiency (L=33 μ H)

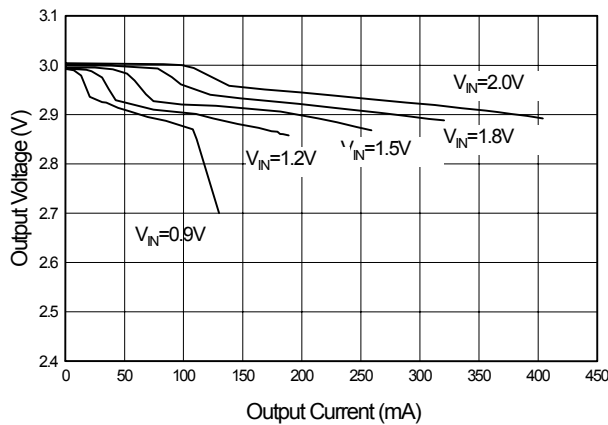


Fig. 3 AIC1639-30 Load Regulation (L=33 μ H)

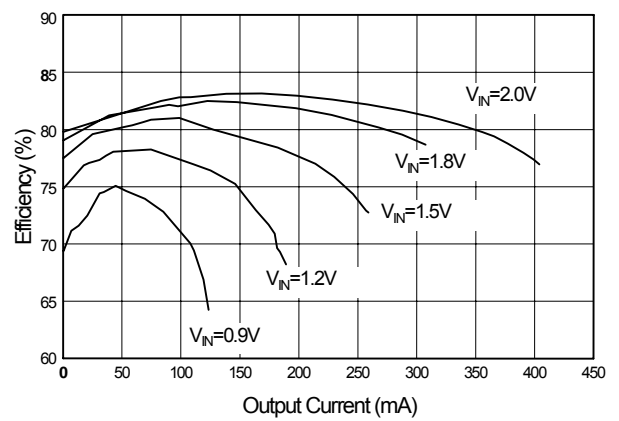


Fig. 4 AIC1639-30 Efficiency (L=33 μ H)

TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

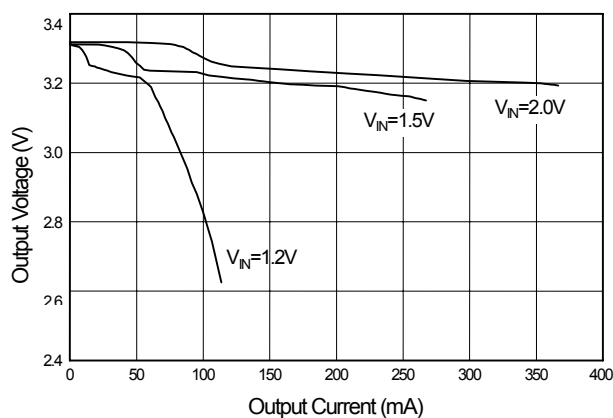


Fig. 5 AIC1639-33 Loading Regulation (L=33 μ H)

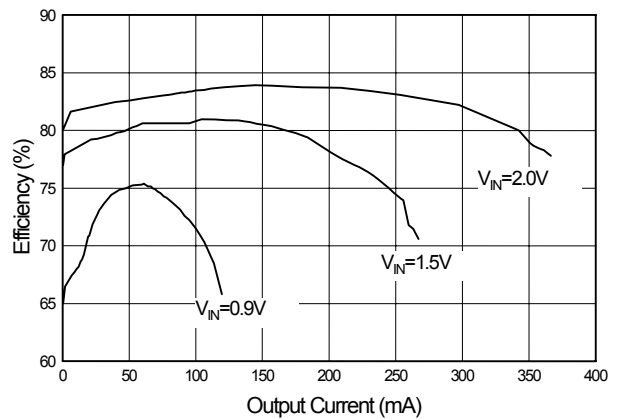


Fig. 6 AIC1639-33 Efficiency (L=33 μ H)

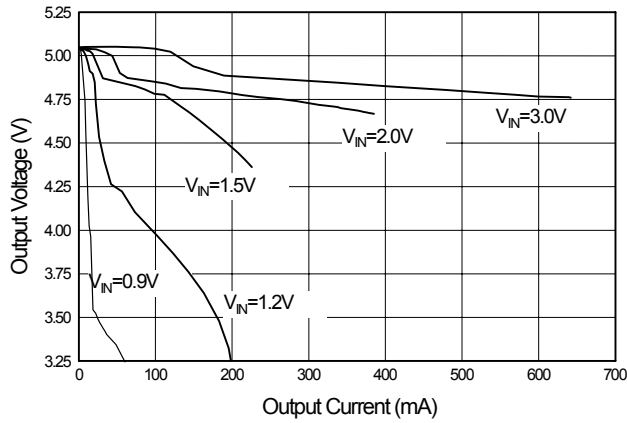


Fig. 7 AIC1639-50 Load Regulation (L=33µH)

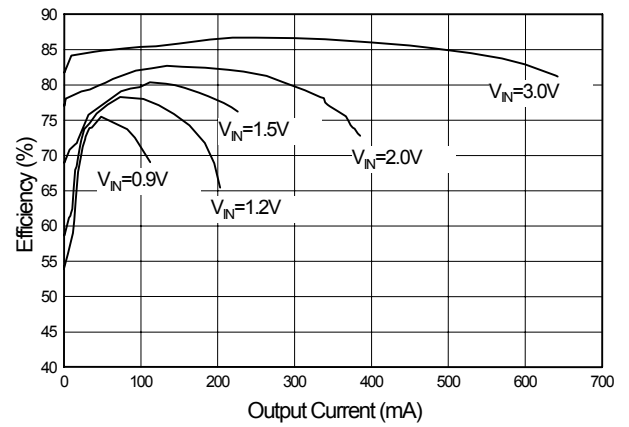


Fig. 8 AIC1639-50 Efficiency (L=33µH)

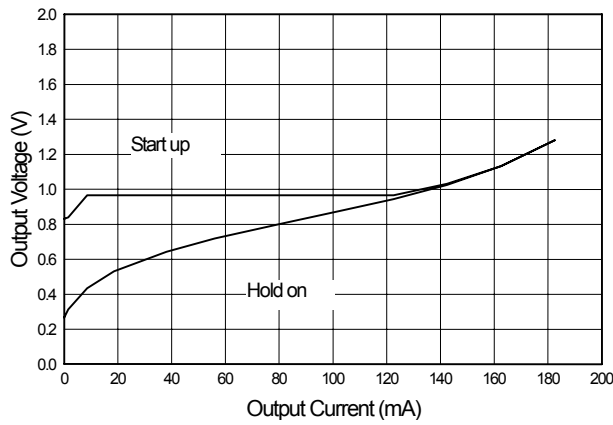


Fig. 9 AIC1639-27 Start-up & Hold-on Voltage (L=33µH)

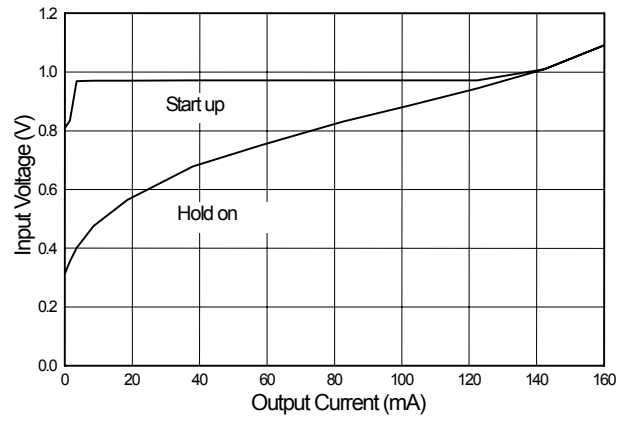


Fig. 10 AIC1639-30 Start-up & Hold-on Voltage (L=33µH)

TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

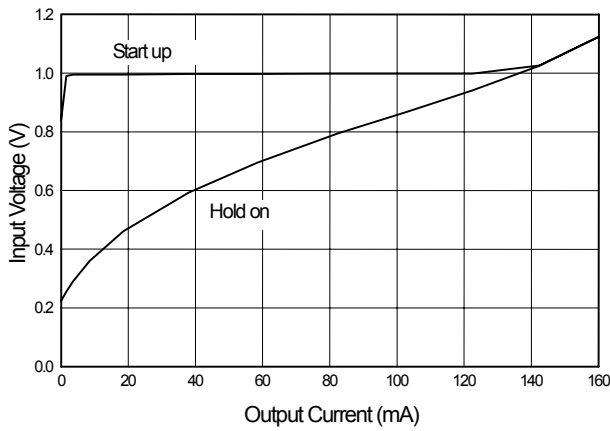


Fig. 11 AIC1639-33 Start-up & Hold-on Voltage (L=33 μ H)

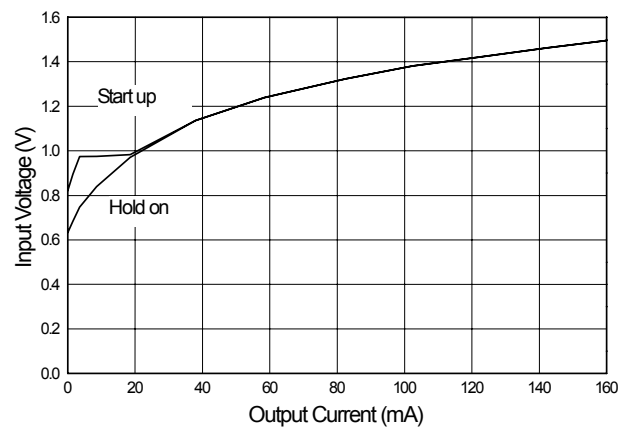


Fig. 12 AIC1639-50 Start-up & Hold-on Voltage (L=33 μ H)

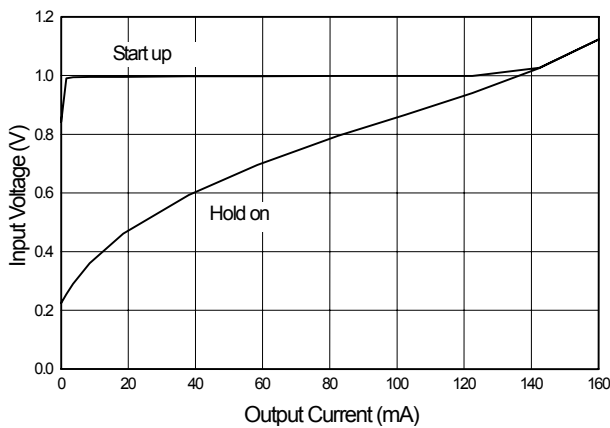


Fig. 13 AIC1639-33 Start-up & Hold-on Voltage (L=33 μ H)

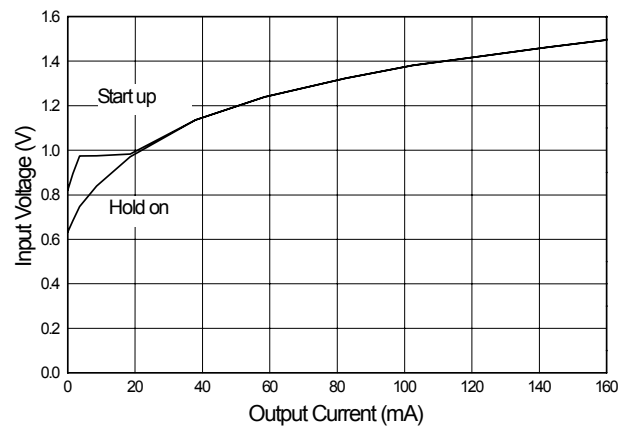


Fig. 14 AIC1639-50 Start-up & Hold-on Voltage (L=33 μ H)

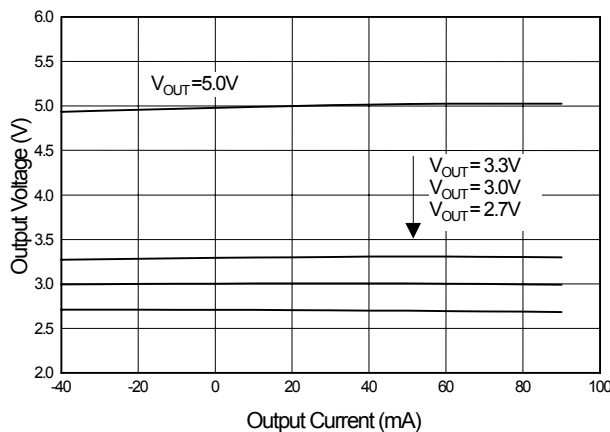


Fig. 15 AIC1639 Output Voltage vs. Temperature

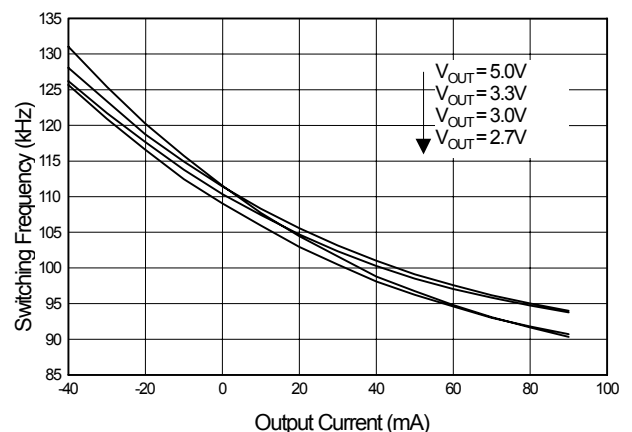


Fig. 16 AIC1639 Switching Frequency vs. Temperature

TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

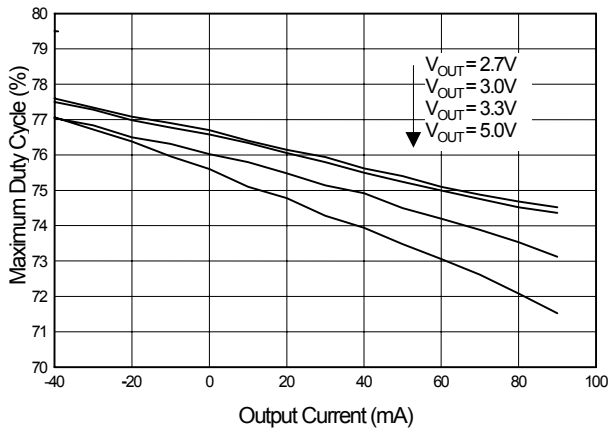


Fig. 17 AIC1639 Maximum Duty Cycle vs. Temperature

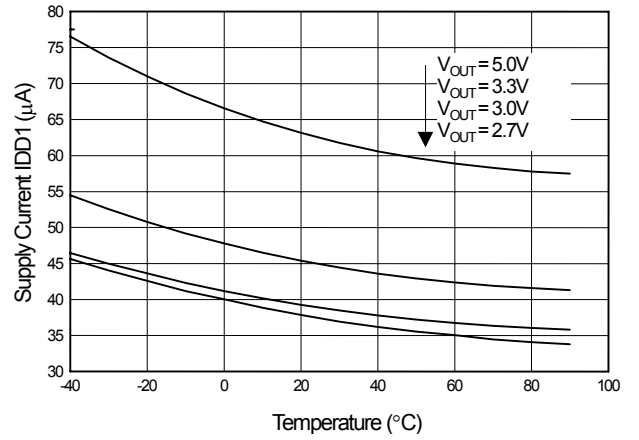


Fig. 18 AIC1639 Supply Current vs. Temperature

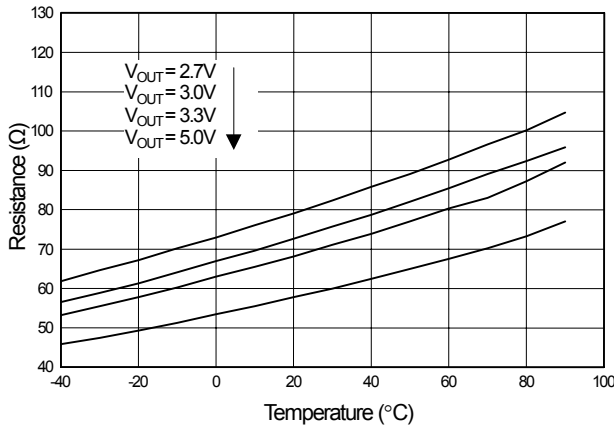


Fig. 19 AIC1639 EXT "L" On-Resistance

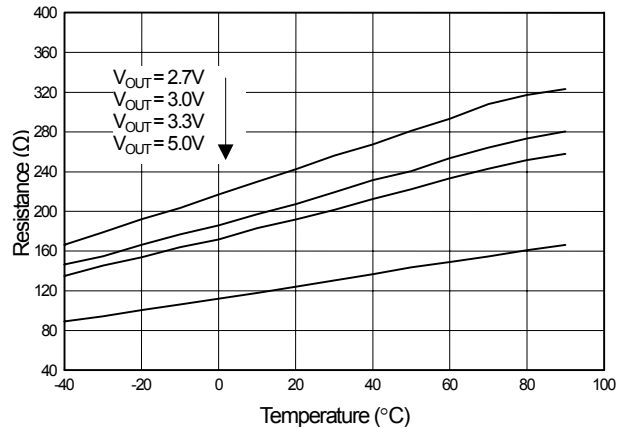
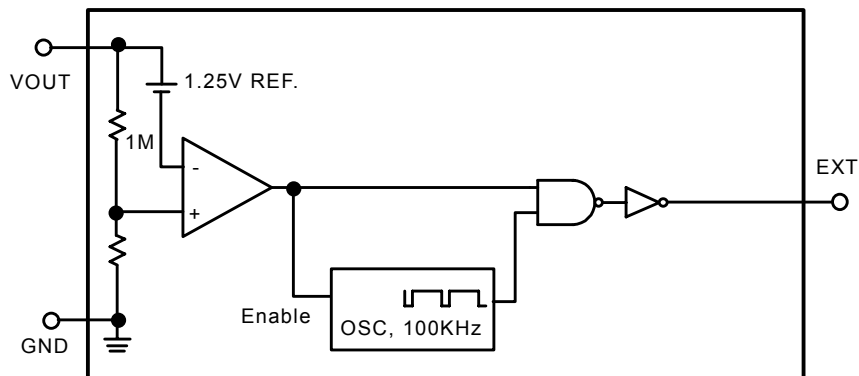


Fig. 20 AIC1639 EXT "H" On-Resistance

■ BLOCK DIAGRAM



■ PIN DESCRIPTIONS

- PIN 1 : GND - Ground. Must be low impedance; solder directly to ground plane.
- PIN 2 : VOUT - IC supply pin. Connect VOUT to the regulator output.

- PIN 3: EXT - Push Pull driver output for external power switch.

■ APPLICATION INFORMATION

GENERAL DESCRIPTION

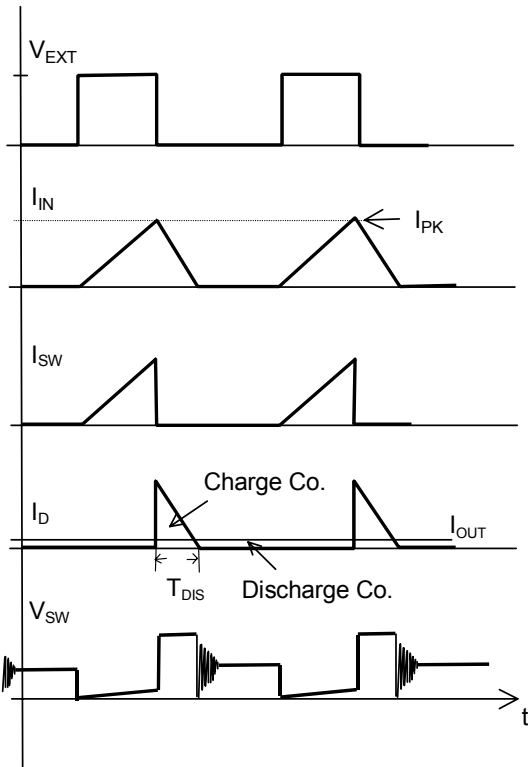
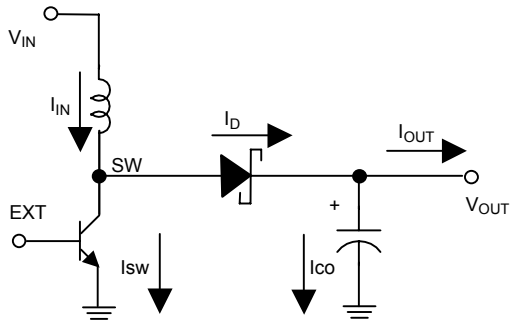
AIC1639 PFM (pulse frequency modulation) controller ICs combine a switch mode regulator, push pull driver (AIC1639), precision voltage reference, and voltage detector in a single monolithic device. They offer both extreme low quiescent current, high efficiency, and very low gate threshold voltage to ensure start-up with low battery voltage (0.8V typ.). Designed to maximize battery life in portable products, and minimize switching losses by only switching as needed service the load.

PFM controllers transfer a discrete amount of energy per cycle and regulate the output voltage by modulating switching frequency with the constant turn-on time. Switching frequency depends on load, input voltage, and inductor value, and it can range up to 100KHz.

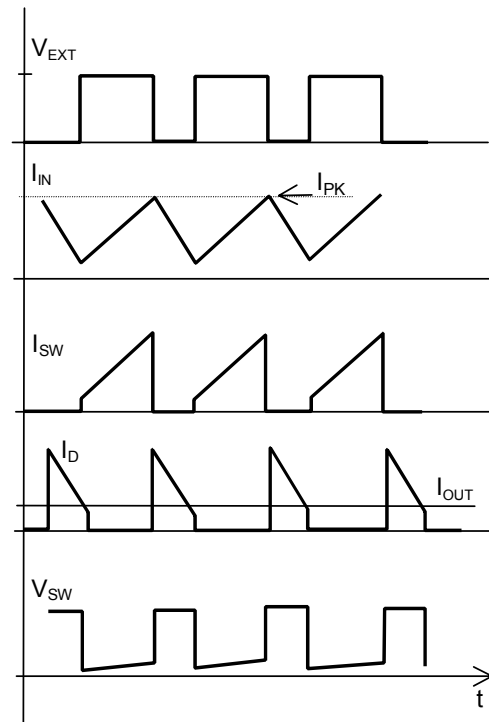
When the output voltage drops, the error comparator enables 100kHz oscillator that turns on the MOSFET around 7.5 μ S and 2.5 μ S off time. Turning on the MOSFET allows inductor current to ramp up, storing energy in a magnetic field. When MOSFET turns off that forces inductor current through diode to the output capacitor and load. As the stored energy is depleted, the current ramp down until the diode turns off. At this point, inductor may ring due to residual energy and stray capacitance. The output capacitor stores charge when current flowing through the diode is high, and release it when current is low, thereby maintaining a steady voltage across the load.

As the load increases, the output capacitor discharges faster and the error comparator initiates cycles sooner, increasing the switching frequency. The maximum duty cycle ensure adequate time for energy transfer to output during

the second half each cycle. Depending on circuit, PFM controller can operate in either discontinuous mode or continuous conduction mode. The continuous conduction mode means that the inductor current does not ramp to zero during each cycle.



Discontinuous Conduction Mode



Continuous Conduction Mode

At the boundary between continuous and discontinuous mode, output current (I_{OB}) is determined by

$$I_{OB} = \left(\frac{V_{IN}}{V_{OUT} + V_D} \right) * \frac{1}{2} * \frac{V_{IN}}{L} * T_{ON} * (1 - x)$$

where V_D is the diode drop,

$$X = (R_{ON} + R_S) * \frac{T_{ON}}{L}$$

R_{ON}= Switch turn on resistance, R_S= Inductor DC resistance

T_{ON} = Switch ON time

In the discontinuous mode, the switching frequency (F_{sw}) is

$$F_{SW} = \frac{2(L) * (V_{OUT} + V_D - V_{IN}) * (I_{OUT})}{V_{IN}^2 * T_{ON}^2} * (1 + x)$$

In the continuous mode, the switching frequency is

$$f_{sw} = \frac{1}{T_{ON}} * \frac{(V_{OUT} + V_D - V_{IN})}{(V_{OUT} + V_D - V_{SW})} * \left[1 + \frac{x}{2} * \left(\frac{V_{IN} - V_{SW}}{V_{OUT} + V_D - V_{SW}} \right) \right]$$

$$\cong \frac{1}{T_{ON}} * \left(\frac{V_{OUT} + V_D - V_{IN}}{V_{OUT} + V_D - V_{SW}} \right)$$

where V_{sw} = switch drop and proportion to output current.

INDUCTOR SELECTION

To operate as an efficient energy transfer element, the inductor must fulfill three requirements. First, the inductance must be low enough for the inductor to store adequate energy under the worst case condition of minimum input voltage and switch ON time. Second, the inductance must also be high enough so maximum current rating of AIC1639 and inductor are not exceeded at the other worst case condition of maximum input voltage and ON time. Lastly, the inductor must have sufficiently low DC resistance so excessive power is not lost as heat in the windings. But unfortunately this is inversely related to physical size.

Minimum and Maximum input voltage, output voltage and output current must be established before and inductor can be selected.

In discontinuous mode operation, at the end of the switch ON time, peak current and energy in the inductor build according to

$$I_{PK} = \left(\frac{V_{IN}}{R_{ON} + R_S} \right) * \left(1 - \exp\left(-\frac{R_{ON} + R_S}{L} * T_{ON}\right) \right)$$

$$\cong \left(\frac{V_{IN}}{L} \right) * (T_{ON}) * \left(1 - \frac{x}{2} \right)$$

$$\cong \frac{V_{IN}}{L} * T_{ON}$$

(simple lossless equation), where

$$X = (R_{ON} + R_S) * \frac{T_{ON}}{L}$$

$$E_L = \frac{1}{2} L * I_{PK}^2$$

Power required from the inductor per cycle must be equal or greater than

$$\frac{P_L}{f_{sw}} = (V_{OUT} + V_D - V_{IN}) * (I_{OUT}) * \left(\frac{1}{f_{sw}} \right)$$

In order for the converter to regulate the output.

When loading is over IOB, PFM controller operates in continuous mode. Inductor peak current can be derived from

$$I_{PK} = \left(\frac{V_{OUT} + V_D - V_{SW}}{V_{IN} - V_{SW}} - \frac{x}{2} \right) * I_{OUT} + \left(\frac{V_{IN} - V_{SW}}{2L} \right) * T_{ON} * \left(1 - \frac{x}{2} \right)$$

Valley current (I_V) is

$$I_V = \left(\frac{V_{OUT} + V_D - V_{SW}}{V_{IN} - V_{SW}} - \frac{x}{2} \right) * I_{OUT} * \left(\frac{V_{IN} - V_{DE}}{2L} \right) * T_{ON} * \left(1 - \frac{x}{2} \right)$$

Table 1 Indicates resistance and height for each coil.

Power Inductor Type	Inductance (μH)	Resistance (Ω)	Rated Current (A)	height (mm)
Sumida SMT Type CD54	47	0.25	0.7	4.5
	100	0.50	0.5	
Hold SMT Type PM54	47	0.25	0.7	4.5
	100	0.50	0.5	
Hold SMT Type PM75	33	0.11	1.2	5.0
Huan Feng PIN Type V0810	33	40m	2	10.0

CAPACITOR SELECTION

A poor choice for a output capacitor can result in poor efficiency and high output ripple. Ordinary aluminum electrolytic, while inexpensive may have unacceptably poor ESR and ESL. There are low ESR aluminum capacitors for switch mode DC-DC converters which work much better than general-purpose unit. Tantalum capacitors provide still better performance at more expensive. OS-CON capacitors have extremely low ESR in a small size. If capacitance is reduced, output ripple will increase.

Most of the input supply is supplied by the input bypass capacitor, the capacitor voltage rating should be at least 1.25 times greater than a maximum input voltage.

DIODE SELECTION

Speed, forward drop, and leakage current are the three main consideration in selecting a rectifier diode. Best performance is obtained with Schottky rectifier diode such 1N5819. Motorola makes MBR0530 in surface mount. For lower output power a 1N4148 can be used although efficiency and start-up voltage will suffer substantially.

COMPONENT POWER DISSIPATION

Operating in discontinuous mode, power loss in the winding resistance of inductor can be approximate equal to

$$PD_L = \frac{2}{3} * \left(\frac{T_{ON}}{L} \right) * (R_S) * \left(\frac{V_{OUT} + V_D}{V_{OUT}} \right) * (P_{OUT})$$

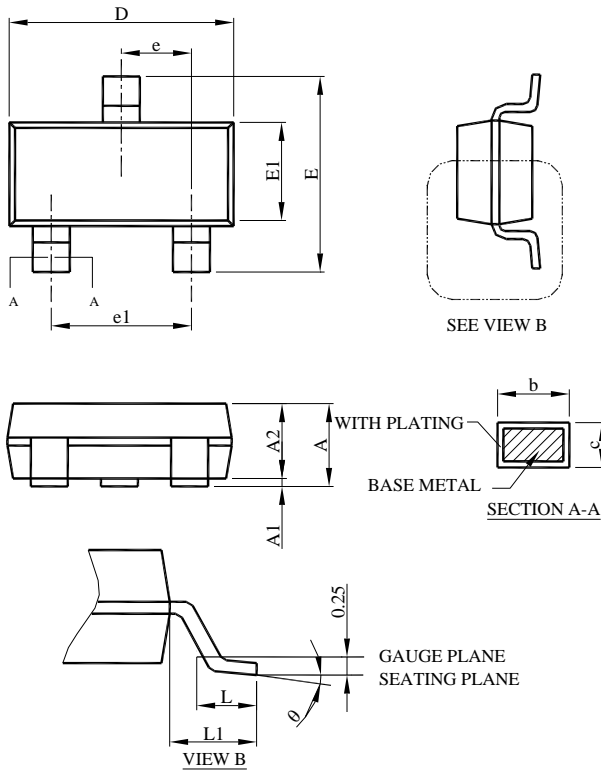
where $P_{OUT} = V_{OUT} * I_{OUT}$; $R_S = \text{Inductor DC R}$;
 $V_D = \text{Diode drop}$.

The power dissipated in a switch loss is

$$PD_{SW} = \frac{2}{3} * \left(\frac{T_{ON}}{L} \right) * (R_{ON}) * (I_{OUT}) * (P_{OUT})$$

The power dissipated in rectifier diode is

$$PD_D = \left(\frac{V_D}{V_{OUT}} \right) * (P_{OUT})$$

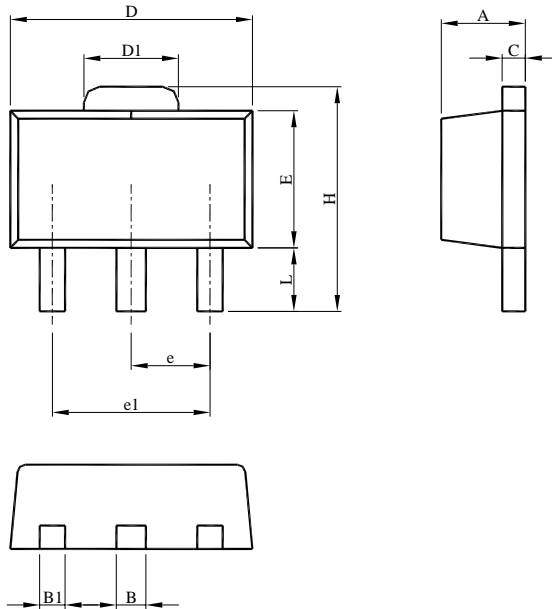
PHYSICAL DIMENSIONS (unit: mm)
● SOT-23


SYMBOL	SOT-23	
	MILLIMETERS	
	MIN.	MAX.
A	0.95	1.45
A1	0.05	0.15
A2	0.90	1.30
b	0.30	0.50
c	0.08	0.22
D	2.80	3.00
E	2.60	3.00
E1	1.50	1.70
e	0.95 BSC	
e1	1.90 BSC	
L	0.30	0.60
L1	0.60 REF	
θ	0°	8°

Note:

- 1.Refer to JEDEC MO-178.
- 2.Dimension D and E1 do not include mold flash, protrusions or gate burrs. Mold flash, protrusion or gate burrs shall not exceed 10 mil per side.
- 3.Controlling dimension is millimeter, converted inch dimensions are not necessarily exact.

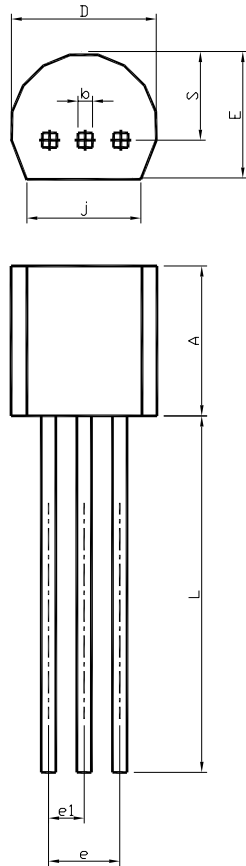
● SOT-89



SYMBOL	SOT-89	
	MILLIMETERS	
	MIN.	MAX.
A	1.40	1.60
B	0.44	0.56
B1	0.36	0.48
C	0.35	0.44
D	4.40	4.60
D1	1.50	1.83
E	2.29	2.60
e	1.50 BSC	
e1	3.00 BSC	
H	3.94	4.25
L	0.89	1.20

Note:
 1.Refer to JEDEC TO-243AA.
 2.Controlling dimension is millimeter, converted inch dimensions are not necessarily exact.

● TO-92



SYMBOL	TO-92	
	MILLIMETERS	
	MIN.	MAX.
A	4.32	5.33
b	0.36	0.47
D	4.45	5.20
E	3.18	4.19
e	2.42	2.66
e1	1.15	1.39
j	3.43	
L	12.70	
S	2.03	2.66

Note:
 1.Refer to JEDEC TO-92.
 2.Controlling dimension is millimeter, converted inch dimensions are not necessarily exact.

Note:

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