

23V 2A Step-Down DC/DC Converter

■ FEATURES

- 2A Continuous Output Current
- Programmable Soft Start
- 180mΩ Internal Power MOSFET Switch
- Stable with Low ESR Output Ceramic Capacitors
- Up to 95% Efficiency
- 22µA Supply Current in Shutdown Mode
- Fixed 380KHz Frequency
- Thermal Shutdown
- Cycle by Cycle Over Current Protection
- Wide 4.75 to 23V Operating Input Range
- Output Adjustable from 1.22V to 16V
- Under Voltage Lockout

APPLICATIONS

- Networking Products such as DSL Modems
- Distributed Power Systems
- Battery Charger
- Pre-Regulator for Linear Regulators.

DESCRIPTION

The AIC2561 is a non-synchronous step-down regulator with an integrated Power MOSFET. It achieves 2A continuous output current over a wide input supply range with excellent load and line regulation.

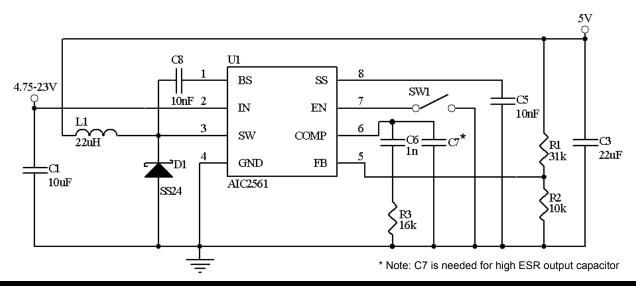
Current mode operation provides fast transient response and eases loop stabilization.

Fault condition protection includes cycle-by-cycle current limiting and thermal shutdown. Adjustable soft-start reduces the stress on the input source and the output overshoot at turn-on. In shutdown mode, the regulator draws 22µA of supply current.

The AIC2561 requires a minimum number of readily available external components.

The AIC2561 is available in a SOP-8 Package.

■ TYPICAL APPLICATIONS CIRCUIT



Analog Integrations Corporation

Si-Soft Research Center

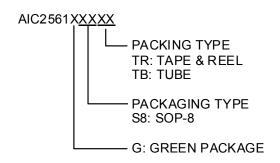
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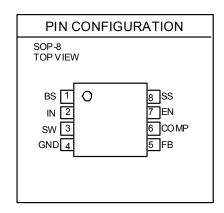
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ORDERING INFORMATION





Example:

AIC2561GS8TR

→ in SOP-8 Green Package and Tape & Reel Packing Type

ABSOLUTE MAXIMUM RATINGS

IN Voltage	24V
SW Voltage	
BS Voltage	
All other pins	
Operating Ambient Temperature Range T _A	
Operating Maximum Junction Temperature T _J	150°C
Storage Temperature Range	-65°C ~ 150°C
Lead Temperature (Soldering 10 Sec.)	260°C
Thermal Resistance Junction to Case SOP-8	
Thermal Resistance Junction to Ambient SOP-8	160°C/W
(Assume no Ambient Airflow)	

Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.



■ ELECTRICAL CHARACTERISTICS

(V_{IN} =12V, unless otherwise specified. Typical values are at T_A =+25°C) (Note1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Shutdown Supply Current		V _{EN} ≤ 0.4V		22	36	μА
Supply Current		V _{EN} ≥ 3V, V _{FB} =1.4V		1.1	1.3	mA
Feedback Voltage	V _{FB}	4.75V ≤ V _{IN} ≤ 23V	1.194	1.222	1.250	V
Error Amplifier Voltage Gain	A _{VEA}			400		V/V
Error Amplifier Transconductance	G _{EA}	$\Delta I_{COMP} = \pm 10 \mu A$	550	830	1150	μ A /V
High-Side Switch On-Resistance	R _{DS(ON)1}			180		mΩ
Low-Side Switch On-Resistance	R _{DS(ON)2}			10		Ω
High-Side Switch Leakage Current		V _{EN} = 0V, V _{SW} = 0V		0	10	μА
Current Limit			2.8	3.4		А
Current Sense to COMP Transconductance	G _{CS}			1.95		A/V
Oscillation Frequency	fs			380		KHz
Short Circuit Oscillation Frequency		V _{FB} = 0V		120		KHz
Maximum Duty Cycle	D _{MAX}	V _{FB} = 0.8V		90		%
EN Shutdown Threshold			1.1	1.5	2.0	V
Enable Pull Up Current		V _{EN} = 0V		1.0		μА
Under Voltage Lockout Threshold		V _{IN} Rising	3.6	4.0	4.4	٧
Under Voltage Lockout Threshold Hysteresis				210		mV
Thermal Shutdown				160		°C

Note 1: Specifications are production tested at T_A =25°C. Specifications over the -40°C to 85°C operating temperature range are assured by design, characterization and correlation with Statistical Quality Controls (SQC).



TYPICAL PERFORMANCE CHARACTERISTICS

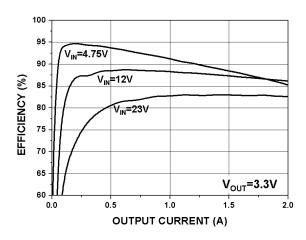


Fig. 1 Efficiency vs. Load Current

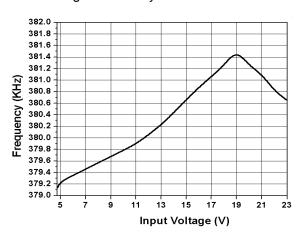


Fig. 3 Switching Frequency vs. Input Voltage

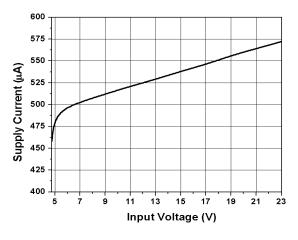


Fig. 5 Supply Current vs. Input Voltage

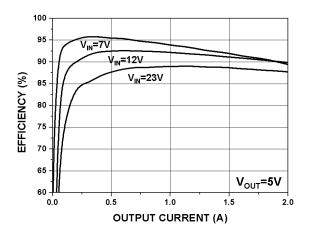


Fig. 2 Efficiency vs. Load Current

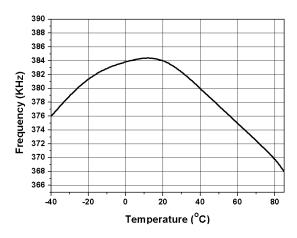


Fig. 4 Switching Frequency vs. Temperature

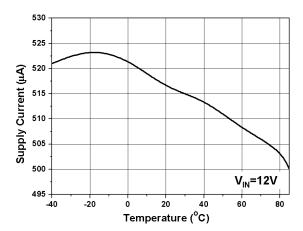


Fig. 6 Supply Current vs. Temperature



■ TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

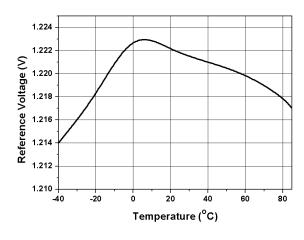


Fig. 7 V_{REF} vs. Temperature

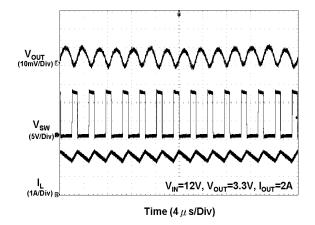


Fig. 8 Output Ripple Voltage

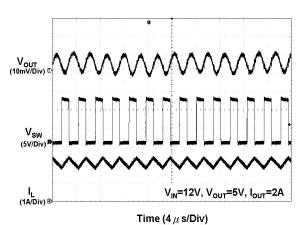


Fig. 9 Output Ripple Voltage

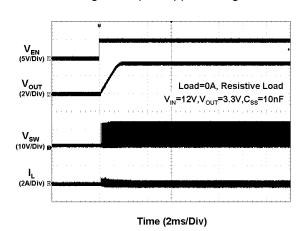


Fig. 10 Startup

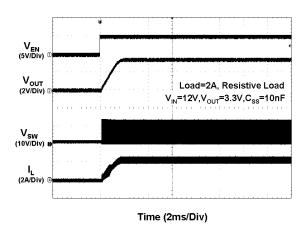


Fig. 11 Startup

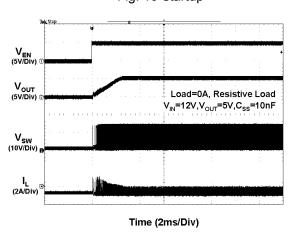


Fig. 12 Startup



■ TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

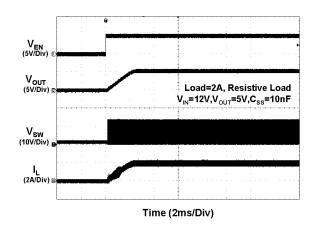


Fig. 13 Startup

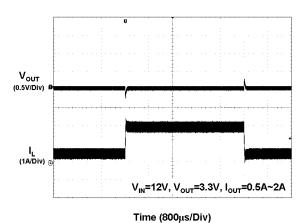


Fig. 14 Load Transient Response

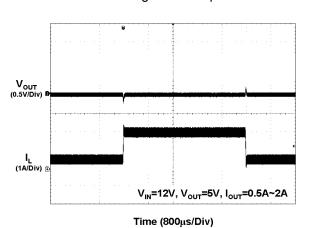
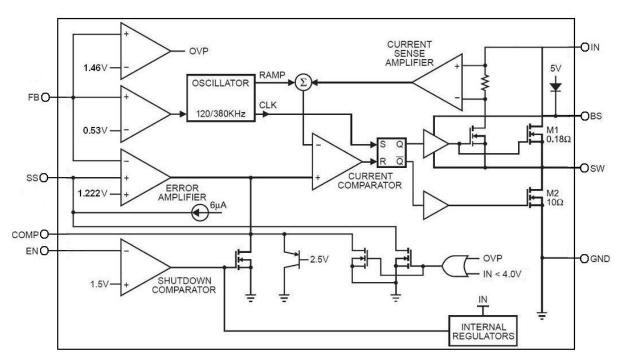


Fig. 15 Load Transient Response



■ BLOCK DIAGRAM



Functional Block Diagram of AIC2561



■ PIN DESCRIPTIONS

PIN1: BS: High Side Gate Drive Boost Input. BS

supplies the drive for the high-side N-Channel MOSFET switch. Connect a 10nF or greater capacitor from SW to

BS to power the high-side switch.

PIN2: IN: Power Input. IN supplies the power to

the IC, as well as the step-down converter switches. Drive IN with a 4.75 to 23V power source. By pass IN to

GND with a suitable large capacitor to eliminate noise on the input to the IC.

PIN3: SW: Power Switching Output. SW is the

switching node that supplies power to the output. Connect the output LC filter from switch to the output load. Note that a capacitor is required from SW to BS to

power the high-side switch.

PIN4: GND: Ground.

PIN5: FB: Feedback Input. FB senses the output

voltage to regulate that voltage. Drive feedback with a resistive voltage divider

from the output voltage.

PIN6: COMP: Compensation Node. COMP is used to

compensate the regulation control loop.

Connect a series RC network form

COMP to GND to compensate the regulation control loop. In some cases,

an additional capacitor from COMP to

GND is required.

PIN 7: EN: Enable Input. EN is a digital input that

turns the regulator on or off. Drive $\ensuremath{\mathsf{EN}}$

high to turn on the regulator. Drive it low

to turn it off. For automatic start-up,

leave EN unconnected.

PIN 8: SS: Soft Star Control Input. SS controls the

soft star period. Connect a capacitor

from SS to GND to set the soft-star $\,$

period. To disable the soft-star feature,

leave the SS pin unconnected.



OMPONENT SELECTION

V _{IN} (V)	V _{OUT} (V)	L₁ (μH)	C ₃ (μF)	R_3 (k Ω)	C ₆ (nF)	R_1 (k Ω)	R_2 (k Ω)
12	1.8	10 (GOTREND GSDRH124-100M)	22 ceramic (Taiyo Yuden EMK325BJ226MM-T)	6.2	3.3	4.75	10
12	2.5	10 (GOTREND GSDRH124-100M)	22 ceramic (Taiyo Yuden EMK325BJ226MM-T)	8.2	2.2	11	10
12	3.3	15 (Lee Yu LYS104S-150M)	22 ceramic (Taiyo Yuden EMK325BJ226MM-T)	10	2.2	17	10
12	5.0	22 (COOPER BUSSMANN DR127-220-R)	22 ceramic (Taiyo Yuden EMK325BJ226MM-T)	16	1.0	31	10

APPLICATION INFORMATION

Operation

The AIC2561 is a fixed-frequency and high efficiency step-down DC/DC converter with current-mode PWM control architecture. selecting appropriate circuit components, it can achieve fast transient response. During normal operation, the AIC2561 can regulate its output voltage through a feedback control circuit, which is composed of an error amplifier; a current comparator and several control signal generators. By comparing the feedback voltage to the reference voltage of 1.222V, the error amplifier varies the voltage at COMP pin. The voltage at COMP pin is compared with the summing signal of current sensing signal and slope compensation signal to determine the duty cycle of internal power switch.

Current Limitation

The AIC2561 provides current limit function by using an internal sensing resistor. When the internal power switch turns on, current follows through the internal sensing resistor. And current amplifier senses the voltage, which crosses the

resistor, and amplifies it. While the sensed voltage gets higher than reference voltage, the current limitation function is activated. While the current limitation function is activated, the duty cycle will be reduced to limit the output power to protect the internal power switches.

Short Circuit Protection

While the output is shorted to ground, the switching frequency of AIC2561 will be reduced to third of the normal switching frequency. This lower switching frequency ensures the inductor current has more time to discharge, thereby preventing inductor current runaway. The switching frequency will automatically return to its designed value while short circuit condition is released.

Soft-Start

The AIC2561 provides the soft-start function. Initially, the voltage at SS pin is 0V. Then an internal current source of $6\mu A$ (typ.) charges an external soft-start capacitor. During the soft-start period, the voltage at SS pin will limit the feedback threshold voltage at FB pin. When the voltage at



SS pin is higher than 1.222V, the feedback threshold voltage at FB pin reaches the desired value. The soft-start time can be calculated in accordance with the following equation.

$$t_{SS} = C_{SS} \times \frac{1.222V}{6\mu A}$$

The soft-start capacitor is discharged to GND when the EN pin is connected to GND.

Shutdown

By connecting the EN pin to GND, the AIC2561 can be shut down to reduce the supply current to $22\mu A$ (typ.). At this operation mode, the output voltage of step-down converter is equal to 0V. For automatic startup, leave EN pin unconnected.

Components Selection

Inductor

The inductor selection depends on the current ripple of inductor, the input voltage and the output voltage.

$$L \ge \frac{V_{OUT}}{f_{OSC} \cdot \Delta I_L} \left(1 - \frac{V_{OUT}}{V_{IN}} \right)$$

Accepting a large current ripple of inductor allows the use of a smaller inductance. However, higher current ripple of inductor can cause higher output ripple voltage and large core loss. By setting an acceptable current ripple of inductor, a suitable inductance can be obtained from above equation.

In addition, it is important to ensure the inductor saturation current exceeds the peak value of inductor current in application to prevent core saturation. The peak value of inductor current can be calculated according to the following equation.

$$I_{PEAK} = I_{OUT(max)} + \frac{V_{OUT}}{2 \times f_{OSC} \cdot L} \left(1 - \frac{V_{OUT}}{V_{IN}} \right)$$

Diode

A Schottky diode with low forward drop voltage and fast reverse recovery is the ideal choice for better efficiency. The forward drop voltage of a Schottky diode will result in the conduction losses in the diode, and the diode capacitance (C_T or C_D) will cause the switching losses. Therefore, it is necessary to consider both forward voltage drop and diode capacitance for diode selection. In addition, the rating of selected Schottky diode should be able to handle the input voltage and the maximum peak diode current.

Input Capacitor and Output Capacitor

To prevent the high input voltage ripple and noise resulted from high frequency switching, the use of low ESR ceramic capacitor for the maximum RMS current is recommended. The approximated RMS current of the input capacitor can be calculated according to the following equation.

$$I_{CINRMS} \approx \sqrt{I_{OUT(MAX)}^2 \times \frac{V_{OUT} \left(V_{IN} - V_{OUT}\right)}{V_{IN}^2} + \frac{\Delta I_L^2}{12}}$$

The selection of output capacitor depends on the required output voltage ripple. The output voltage ripple can be expressed as:

$$\Delta V_{OUT} = \frac{\Delta I_{L}}{8 \times f_{OSC} \cdot C_{OUT}} + ESR \cdot \Delta I_{L}$$

For lower output voltage ripple, the use of low ESR ceramic capacitor is recommended.

When choosing the input and output ceramic capacitors, X5R and X7R types are recommended because they retain their capacitance over wider ranges of voltage and temperature than other types.



Soft-Start Capacitor

The soft-start of AIC2561 begins from $V_{\rm SS}$ =0V and ends while $V_{\rm SS}$ reaches 1.222V. During the soft-start period, an internal current source of 6μ A (typ.) charges the soft-start capacitor. Hence, the soft-start capacitor should be large enough to ensure that the output voltage has reached the regulation value before the soft-start function has finished.

Output Voltage Programming

By connecting a resistive divider R_1 and R_2 , the output voltage of AIC2561 step-down converter can be set. V_{OUT} can be calculated as:

$$V_{OUT} = 1.222 \times \left(1 + \frac{R_1}{R_2}\right)$$

The resistive divider should sit as close to FB pin as possible.

Loop Compensation

In order to avoid the poor output voltage ripple and low efficiency caused by instability, AIC2561 requires a proper external compensation network to compensate its feedback loop. In this external compensation network, the compensation resistor, R_3 , and the compensation capacitor, C_6 , are used to set the high-frequency integrator gain and the integrator zero. C_7 is used to cancel the zero caused by the output capacitor and its ESR. While using the ceramic capacitor as the output capacitor, C_7 can be omitted due to the small ESR.

The values of the compensation components given in this data sheet yield a stable control loop

for the given output voltage and capacitor. If different conversions and output capacitors are requires, some values of the compensation components may need to be adjusted to ensure stability.

Layout Consideration

In order to ensure a proper operation of AIC2561, the following points should be managed comprehensively.

- The input capacitor and V_{IN} should be placed as close as possible to each other to reduce the input voltage ripple and noise.
- The output loop, which is consisted of the inductor, the internal power switch, the Schottky diode and the output capacitor, should be kept as small as possible.
- The routes with large current should be kept short and wide.
- Logically the large current on the converter should flow at the same direction.
- In order to prevent the effect from noise, the IC's GND pin should be placed close to the ground of the input bypass capacitor and should be away from the ground of the Schottky diode.
- The FB pin should be connected to the feedback resistors directly and the route should be away from the noise sources.

Fig. 16 to 19 shows the layout diagrams of AIC2561.



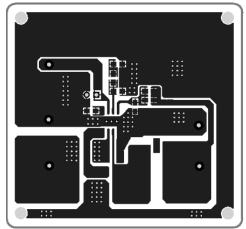


Fig. 16 Top Layer

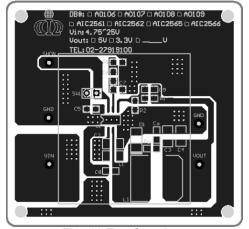


Fig. 18 Top Over Layer

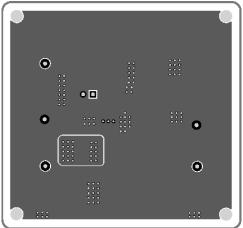


Fig. 17 Bottom Layer

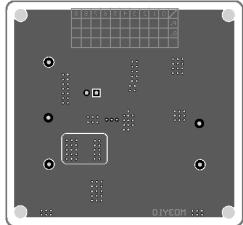
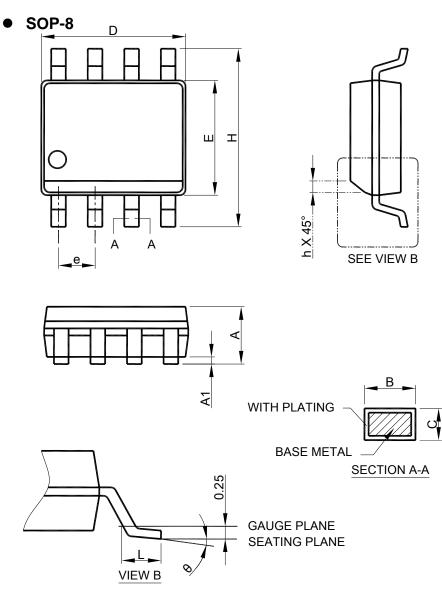


Fig. 19 Bottom Over Layer



■ PHYSICAL DIMENSIONS (unit: mm)



S Y M	SOP-8 MILLIMETERS		
M B			
B O L	MIN.	MAX.	
Α	1.35	1.75	
A1	0.10	0.25	
В	0.33	0.51	
С	0.19	0.25	
D	4.80	5.00	
Е	3.80	4.00	
е	1.27 BSC		
Н	5.80	6.20	
h	0.25	0.50	
L	0.40	1.27	
θ	0°	8°	

- Note: 1. Refer to JEDEC MS-012AA.
 - 2. Dimension "D" does not include mold flash, protrusions or gate burrs. Mold flash, protrusion or gate burrs shall not exceed 6 mil per side .
 - 3. Dimension "E" does not include inter-lead flash or protrusions.
 - 4. Controlling dimension is millimeter, converted inch dimensions are not necessarily exact.

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